

UAVCAN EQUIPMENT ACTUATOR ARRAYCOMMAND							Rev 1.0
Actuator_id[uint8_t]	Command_Type[float16]			Command_Value	Explain		
1~127	UAVCAN_EQUIPMENT_ACTUATOR_COMMAND_COMMAND_TYPE_UNITLESS	0	-1.00~ -0.01	LEFT (Up to the set endpoint)		UAVCAN	
			0	MID = 8192			
			0.01 ~ 1.00	RIGHT (Up to the set endpoint)			
	UAVCAN_EQUIPMENT_ACTUATOR_COMMAND_COMMAND_TYPE_POSITION	1	91~16300	SERVO Position Value			
	UAVCAN_EQUIPMENT_ACTUATOR_COMMAND_COMMAND_TYPE_FORCE	2	0~4095	SERVO Torque Value			
	UAVCAN_EQUIPMENT_ACTUATOR_COMMAND_COMMAND_TYPE_SPEED	3	0~4095	SERVO Speed Value			
ID + 0x80	Write set value to Servo configuration.			SERVO Register >> Command type (Refer to manual)			FOR
ID + 0x00	Read set value from Servo configuration.						DPC-CAN

UAVCAN EQUIPMENT ACTUATOR STATUS (Only stream from SERVO)					
Actuator_id[uint8_t]	Position[float16]	Force[float16]	Speed[float16]	Power[uint8_t]	Explain
1~127	-1 ~ 1 (Unitless) 0.04 ~ 6.26 (Radians)	0 ~ 4095 (Motor Duty Cycle)	0 ~ x/10000 (Rad/Sec)	0 ~ 100% (Force ratio)	* Unitless or Radians is able to be set on the configuration. * Speed is value of 100 micro-seconds and keep the last. Ex) 2021 = 0.2 rad/Sec. (x =2021, x/10000)